A Vectorized Traversal Algorithm for Ray-Tracing

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Introduction I

- Ray-Tracing:
 - Very Realistic image synthesis.
 - Complex models supported.
 - Basis of many algorithms.
 - Traditionally slow.

Introduction II

- Parallel Raytracers
 - Breadth-first traversal.
 - SIMD aware.
 - Some approaches use GPU.
 - High performance \rightarrow

Interactive / Real-Time RayTracing.

Previous work Classic algorithm

Traversal algorithm: Once per ray



Previous Work Wald's algorithm I

- Coherent rays:
 - Rays with the same origin and very similar direction will very probably hit the same objects.

 The algorithm uses a kd-tree and traverses it with 4-ray packets.

Parallelism using Intel SIMD: SSE.

Previous Work Wald's algorithm II

• Four ray traversal.



Our Proposal Motivation

- Wald's algorithm limitations:
 - The gain in efficiency increases with ray coherency.
 - It's easy to select coherent primary rays in Ray-Tracing or Path-Tracing.
 - For secundary rays in Ray-Tracing, or other applications, rays are not coherent.
 - Gain is therefore smaller.

Our Proposal Motivation II

 With non-coherent rays, packets tend to break, decreasing parallelism.



Our Proposal Description

 We propose traversing the kd-tree only once but with all rays at the same time.

- Rays are classified during the traversal process:
 - No additional effort needed.
 - Coherence is increased in terminal nodes.
- We aim for maximum parallelization.

Our Proposal Traversal Algorithm I

• Traversal for *n* rays.



Our Proposal Traversal Algorithm II

Problem:

- Appears when looking for the first intersection (typical in raytracing and other applications).
- We want the ability to stop the traversal of a ray when finding its first intersection.
- Different rays may mean different traversal order of the tree.

Our Proposal Traversal Algorithm III

Solution:

- Classify the rays in eight groups according to their director vectors.
- Run the algorithm for each group.

Our Proposal Advantages

- Advantages:
 - If 2 or more rays cross the same node, they will do it together.
 - Increases the possibilities of having rays available to process in parallel.
 - Non-coherent rays will be classified when going down the tree.
 - The number of traversals of the tree, and the number of triangle accesses is reduced.

Our Proposal Memory layout of rays I

- A global data structure for the rays:
 - Stores all rays and their attributes (director vector, origin, intersected triangle id...)
- A ray stack:
 - Stores only the values for the ray traversal depending on the current node.
 - Pointer to the rest of the information in the structure above.
 - SSE optimized "Structure of Vectors".

Our Proposal Memory layout of rays II



State of the Ray Stack in node C:



Performance I

 Tests with coherent rays (Ray-Tracing's primary rays – 1 ray per pixel)

- Classic algorithm, 1 traversal per ray.
- Wald's algorithm, 1 traversal per 4-ray packet.
- Wald's algorithm, 1 traversal per 64-ray packet.
- Proposed algorith, 1 traversal for each group of rays with direction vector in the same octant.

Test with non coherent rays

Random rays with uniform distribution.

Performance II



Dragon 0,8 M tri. Stanford Bunny 0,069 M tri.

Happy Buddha 1,1 M tri.

Performance III



Buddha, 1.1MTri, 1280x1024

Conclusions & Future Work

- Our technique allows:
 - More parallelization to be extracted even for noncoherent rays.
 - Visiting each node at most eight times. Less access to nodes and their triangles.
- Future work: larger SIMD width \rightarrow GPU